

H.W. 2 Use G-S and Jacobi to solve

$$\left. \begin{array}{l} 2x_1 - x_2 + x_3 = -1 \\ 3x_1 + 3x_2 + 9x_3 = 0 \\ 3x_1 + 3x_2 + 5x_3 = 4 \end{array} \right\} \begin{array}{l} X^{(0)} = (0.5, 1.5, -0.5) \\ \text{Ans: } (1, 2, -1) \end{array}$$

c) Bisection method - تابع الى الموضوع الاول

It is simple but slowly convergent method for determine a zero of $f(x)$ when $f(x)$ is continuous.

It is based on the intermediate theory. Suppose the continuous fun. $f(x)$ defined on the interval $[a, b]$ is given with $f(a) < 0$ & $f(b) > 0$, then there exist c , $a < c < b$.

Steps there solution:-

Given a continuous fun. $f(x)$ with an interval $[a_0, b_0]$ and satisfying $f(a_0) f(b_0) < 0$

1) compute $C_n = \frac{1}{2} (a_n + b_n)$, $n = 0, 1, 2, \dots$

2) if $C_n \neq 0$, and $f(a_n) f(C_n) < 0$, then

Set $a_{n+1} = a_n$, $b_{n+1} = C_n$

Else $a_{n+1} = C_n$, $b_{n+1} = b_n$

3) The iteration is stopped:-

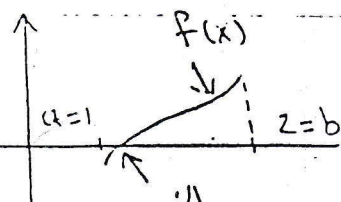
$$\frac{|C_{n-1} - C_n|}{|C_n|} < \text{tolerance } (\epsilon)$$

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Ex₂ $F(x) = x^3 + 4x^2 - 10$ has a root in $[1, 2]$ use bisection method to find that root.

$$f(a) = f(1) = 1 + 4 - 10 = -5$$

$$f(b) = f(2) = 2^3 + 4 \times 4 - 10 = 14$$



n	a_n	b_n	c_n	$f(a_n)$	$f(c_n)$
0	1	2	1.5	-Ve	+Ve
1	1	1.5	1.25	-Ve	-Ve
2	1.25	1.5	1.375	-Ve	+Ve
3	1.25	1.375	1.3125	-Ve	-Ve
11	1.364746	1.365234	1.364990	-Ve	-Ve
12	1.364990	1.365234	1.365112	-Ve	-Ve

$$\left| \frac{c_{11} - c_{12}}{c_{12}} \right| = 8.9 \times 10^{-5}$$

H.W₂ $F(x) = x^3 - x - 1$ has a root in $[1, 2]$ use bisection method to find that root assume $\epsilon = 10^{-2}$

Ans: 1.3203125

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Z.T

1) (a,b), 2 (الفردية), 3, 4, 6, 7

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Sheet Z-transform

Q-6, c)

$$x(n+2) - x(n+1) + 0.5x(n) = 1, \quad x(0) = 2, \quad x(1) = 3$$

$$Z \{ x(n+p) \} = Z^p \left\{ X(Z) - \sum_{k=0}^{p-1} x(k) Z^{-k} \right\}$$

$$\{ Z^2 X(Z) - Z^2 x(0) - Z x(1) \} = \{ Z X(Z) - Z x(0) \} +$$

$$0.5 X(Z) = \frac{Z}{Z-1}$$

$$X(Z) = \frac{2Z^2 - Z}{(Z-1)(Z^2 - Z + 0.5)} = \frac{2Z^2 - Z}{(Z-1) \left\{ \left(Z - \frac{1}{2} \right)^2 + \frac{1}{4} \right\}}$$

نروض I.C ونفوض الحدود

$$= \frac{2Z^2 - Z}{(Z-1) \left\{ \left(Z - \frac{1}{2} \right) + j \frac{1}{2} \right\} \left\{ \left(Z - \frac{1}{2} \right) - j \frac{1}{2} \right\}}$$

$$X(Z) = \frac{2Z^2 - Z}{(Z-1) \left\{ Z - \left(\frac{1}{2} - j \frac{1}{2} \right) \right\} \left\{ Z - \left(\frac{1}{2} + j \frac{1}{2} \right) \right\}}$$
$$= \frac{A}{Z-1} + \frac{B}{Z - \left(\frac{1}{2} - j \frac{1}{2} \right)} + \frac{C}{Z - \left(\frac{1}{2} + j \frac{1}{2} \right)}$$

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Numerical method for 1-st order D.E :-

A D.E of the 1-st order is of the form

$$\dot{y} = f(x, y) \quad \text{--- (1)}$$

$$y(x_0) = y_0 = \text{initial value}$$

which is also called an initial value problem

eq. (1) can be solved using

1. Euler method
2. Runge-kutta (R-k) method

1) Euler method :-

It is an approximation of the curve $y(x)$ by polygon

$$\dot{y}_0 = \frac{y_1 - y_0}{h}$$

Exact Value $\left\{ \begin{array}{l} y(x_0) \\ y(x_1) \\ y(x_2) \end{array} \right.$

$$h = x_{n+1} - x_n = \text{step size}$$

$$\therefore y_1 = y_0 + h \dot{y}_0$$

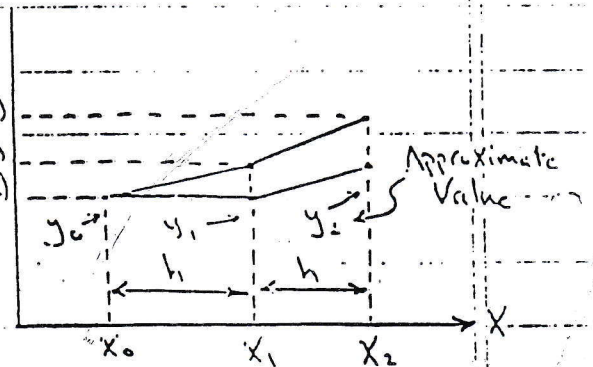
using Taylor series, then

$$y_{n+1} = y_n + h \dot{y}_n = y_n + h f(x_n, y_n)$$

is called Euler method (App. solution)

Note:- The omission of the further terms of the above equation causes error (Truncation)

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$$\int u \cdot dv = u \int v \cdot du - \int u \cdot dv \quad , \quad u = x, \quad dv = e^x$$

$$= x(e^x) - \int 1 \cdot e^x dx \quad (122)$$

error).

To Find the exact solution

$$1) \bar{y} + f(x)y = r(x)$$

نضاه المعادلة

$$2) y(x) = e^{-l} \left\{ \int e^l r(x) dx + c \right\} = \text{Exact sol.}$$

$$l = \int f(x) dx$$

Ex: Find the exact solution of $\bar{y} = 2y$ if $y(0) = 1$

$$\bar{y} - 2y = 0$$

$$\therefore f(x) = -2, \quad r(x) = 0$$

$$l = \int f(x) dx = \int -2 dx = -2x$$

$$\therefore y(x) = e^{2x} \left\{ \int e^{-2x} (0) dx + c \right\}$$

$$y(x) = e^{2x} c$$

لايجاد قيمة الثابت نغوض بـ $x=0$

$$1 = e^0 c \quad \therefore c = 1$$

$$y(x) = e^{2x}$$

(دائماً الحل المصنوع يكون ببساطة x)

Ex: Use Euler method to solve $\bar{y} = x + y$,

$h = 0.2, n = 5, y(0) = 0$ calculate the error?

$$y_{n+1} = y_n + 0.2(x_n + y_n) \leftarrow \text{APP. sol.}$$

$$y(x_n) = e^x - x - 1 = \text{Exact sol. (as H.w)}$$

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steps of solution :-

given an initial value problem

$$\dot{y} = f(x, y), y(x_0) = y_0 \text{ \& } x_{n+1} = x_0 + (n+1)h$$

$$A_n = hf(x_n, y_n)$$

$$B_n = hf\left\{x_n + \frac{h}{2}, y_n + \frac{A_n}{2}\right\}$$

$$C_n = hf\left\{x_n + \frac{h}{2}, y_n + \frac{B_n}{2}\right\}$$

$$D_n = hf\{x_n + h, y_n + C_n\}$$

$$y_{n+1} = y_n + \frac{1}{6}(A_n + 2B_n + 2C_n + D_n)$$

Ex: Solve using (R-K) method

— $\dot{y} = x + y, h = 0.2, n = 5, y(0) = 0$, calculate the error.

Solution :- $\dot{y} = f(x, y) = x_n \oplus y_n$

$$A_n = hf(x_n, y_n) = 0.2(x_n \oplus y_n) \quad \text{--- (1)}$$

$$B_n = 0.2 \left\{x_n + 0.1 \oplus y_n + \frac{A_n}{2}\right\} \quad \text{--- (2)}$$

نعوض (1) بـ (2)

$$B_n = 0.22(x_n + y_n) + 0.02 \quad \text{--- (3)}$$

$$C_n = 0.2 \left\{x_n + 0.1 \oplus y_n + \frac{B_n}{2}\right\} \quad \text{--- (4)}$$

نعوض (3) بـ (4)

$$C_n = 0.222(x_n + y_n) + 0.022 \quad \text{--- (5)}$$

$$D_n = 0.2 \left\{x_n + 0.2 \oplus y_n + C_n\right\} \quad \text{--- (6)}$$

نعوض (5) بـ (6)

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$$D_n = 0.2444 (X_n + Y_n) + 0.0444 \quad \text{--- (7)}$$

$$\therefore Y_{n+1} = Y_n + \frac{1}{6} (A_n + 2B_n + 2C_n + D_n) \quad \text{--- (8)}$$

نعرض المعادلات 7, 5, 3, 1 في المعادلات أعلاه (8)

$$Y_{n+1} = Y_n + 0.2214 (X_n + Y_n) + 0.0214 = \text{App. Sol.}$$

$$y(X_n) = e^x - x - 1$$

$$= \text{Exact sol. (as H.w)}$$

n	X _n	Y _n	Y _{n+1}	y(X _n)	Error
0	0	0	Y ₁ = 0.0214	0	0
1	0.2	Y ₁ = 0.0214	Y ₂ = 0.091818	0.0214 = y(x ₁)	0
2	0.4	0.091818	0.222107	0.0918	1.8 × 10 ⁻⁵
3	0.6	0.222107	0.425521	0.222	1.7 × 10 ⁻⁴
4	0.8	0.425521	0.718251	0.4255	2.1 × 10 ⁻⁵
5	1	0.718251	1.120071	0.718	2.5 × 10 ⁻⁴

← حساب نسبة الخطأ →

H.w: Solve using R-k method, $\dot{y} = x^2 + y$, $x_0 = 0$, $y_0 = 1$, $n = 8$, $h = 0.025$. Calculate the error.

$$y(x) = \text{Exact sol.} = 3e^x - x^2 - 2x - 2 \quad (\text{as H.w})$$

Numerical Differentiation:

1) Difference formula.

2) Three points formula.

1) Difference formula:

$$f'(x_0) = \frac{f(x_0+h) - f(x_0)}{h} - \frac{h}{2} f''(x) \quad , h \neq 0$$

error

If $h > 0$, it is called forward difference formula.

If $h < 0$, = = = backward = = =

Ex 2 Find $f'(1.8)$ for $f(x) = \ln x$ using $h = 0.1, 0.01, 0.001$

$$f'(1.8) = \frac{f(1.8+h) - f(1.8)}{h} = \frac{\ln(1.8+h) - \ln(1.8)}{h}$$

h	$f'(1.8)$	$ Error = \frac{h}{2} f''(x) = \frac{h}{2} \frac{1}{(1.8)^2}$
0.1	0.540672	0.0154321
0.01	0.554018	0.001543
0.001	0.555401	0.000154

$$f'(x) = 1/x \quad \& \quad f''(x) = -1/x^2$$

Exact sol. = $f'(x) = 1/1.8 = 0.5555$

Error = Exact Sol. - APP. sol.

Sol.

وعليه كلما قلت قيمة h زادت الدقة

2) Three points formula:

In this method the points are equally spaced

$$x_0, x_1 = x_0 + h, x_2 = x_0 + 2h, h \neq 0$$

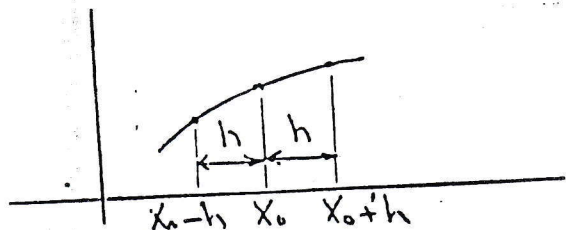
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Formula (1) :-

$$f'(x_0) = \frac{1}{2h} \left\{ -3f(x_0) + 4 \overbrace{f(x_0+h)}^{x_1} - \overbrace{f(x_0+2h)}^{x_2} \right\} + \frac{h^2}{3} \frac{f'''(x)}{\text{error}}$$

Formula (2) :-

$$f'(x_0) = \frac{1}{2h} \left\{ f(x_0+h) - f(x_0-h) \right\} - \frac{h^2}{6} \frac{f'''(x)}{\text{error}}$$



Error = Exact sol. - App. sol.

Formula (2) has the advantage over Formula (1)

1) half the error.

2) evaluated only at two points.

Ex: Find $f'(2)$ for $f(x) = xe^x$, $h=0.1$ using three points Formula (5).

x	$f(x) = xe^x$
1.9	12.703199
2	14.778112
2.1	17.148957
2.2	19.85503

القياس من الجدول

Formula (1) :-

$$f'(2) = \frac{1}{0.2} \left\{ -3f(2) + 4f(2.1) - f(2.2) \right\} = 22.03231$$

Formula (2) :-

$$f'(2) = \frac{1}{0.2} \left\{ f(2.1) - f(1.9) \right\} = 22.22878$$

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$$\text{Exact sol.} = Xe^x + e^x = 2e^2 + e^2 = 22.167168$$

$$\therefore \text{Error} = 22.167168 - \begin{cases} 22.03231 \\ 22.22879 \end{cases} = \begin{cases} 0.1126 \\ -0.0616 \end{cases}$$

Exact App.

Numerical solution of non linear system:

Non linear system can be solved by using:

- 1) Fixed point method (Jacobi & G-S methods).
- 2) Newton method.

1) Fixed point method:

The nonlinear system is in the form:

$$f_1(x_1, x_2, \dots, x_n) = f_1(x) = 0$$

$$f_2(x_1, x_2, \dots, x_n) = f_2(x) = 0$$

$$\vdots$$
$$f_n(x_1, x_2, \dots, x_n) = f_n(x) = 0$$

$$X = (x_1, x_2, \dots, x_n)$$

$$F(x) = \{f_1(x), f_2(x), \dots, f_n(x)\}$$

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Ex2 solved the nonlinear sys.

$$f_1(x_1, x_2, x_3) = 3x_1 - \cos(x_2 x_3) - 1/2 = 0$$

$$f_2(x_1, x_2, x_3) = x_1^2 - 81(x_2 + 0.1)^2 + \sin x_3 + 1.06 = 0$$

$$f_3(x_1, x_2, x_3) = e^{-x_1 x_2} + 20x_3 + \frac{10\pi - 3}{3} = 0$$

$$X^{(0)} = \begin{matrix} 0.1 & 0.1 & -0.1 \\ x_1^{(0)} & x_2^{(0)} & x_3^{(0)} \end{matrix}$$

a) Jacobi method 2-

$$X_1^{(k)} = \frac{1}{3} \cos(X_2^{(k-1)} X_3^{(k-1)}) + 1/6$$

$$X_2^{(k)} = \frac{1}{9} \left\{ [X_1^{(k-1)}]^2 + \sin X_3^{(k-1)} + 1.06 \right\}^{1/2} - 0.1$$

$$X_3^{(k)} = \frac{1}{20} e^{-X_1^{(k-1)} X_2^{(k-1)}} - \frac{10\pi - 3}{60}$$

k	$X_1^{(k)}$	$X_2^{(k)}$	$X_3^{(k)}$
0	0.1	0.1	-0.1
1	0.499983	0.0094411	-0.523101
2	0.499995	0.00002	-0.523633
3	0.5	0.00001	-0.523598
4	=	3×10^{-8}	=
5	=	2×10^{-8}	=

$$X \cong 0.5, 0, -0.523598$$

$X_1 \quad X_2 \quad X_3$

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بمعادلات السؤال

b) G-S method 2-

$$X_1^{(k)} = \frac{1}{3} \cos X_2^{(k-1)} X_3^{(k-1)} + 1/6$$

$$X_2^{(k)} = \frac{1}{9} \left\{ [X_1^{(k)}]^2 + \sin X_3^{(k-1)} + 1.06 \right\}^{1/2} - 0.1$$

$$X_3^{(k)} = \frac{1}{20} e^{-X_1^{(k)} X_2^{(k)}} - \frac{10\pi - 3}{60}$$

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k	$X_1^{(k)}$	$X_2^{(k)}$	$X_3^{(k)}$
0	-0.1	0.1	-0.1
1	0.499983	0.02222	-0.523046
2	0.499977	0.00002	-0.523598
3	0.5	4×10^{-8}	-0.523598
4	=	0	=

$$\therefore X \approx \begin{matrix} 0.5 & , & 0 & , & -0.523598 \\ X_1 & & X_2 & & X_3 \end{matrix}$$

2) Newton's method

$$X_{n+1} = X_n - \frac{f(X_n)}{f'(X_n)}, \quad f' \neq 0 \text{ for 1-Variable}$$

$$X^{(k)} = X^{(k-1)} - J[X^{(k-1)}]^{-1} \cdot F[X^{(k-1)}] \quad \text{--- ①}$$

$$\begin{bmatrix} X_1^{(k)} \\ \vdots \\ X_n^{(k)} \end{bmatrix} = \begin{bmatrix} X_1^{(k-1)} \\ \vdots \\ X_n^{(k-1)} \end{bmatrix} - \begin{bmatrix} \frac{\partial F_1}{\partial X_1} & \frac{\partial F_1}{\partial X_2} & \dots & \frac{\partial F_1}{\partial X_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial F_n}{\partial X_1} & \frac{\partial F_n}{\partial X_2} & \dots & \frac{\partial F_n}{\partial X_n} \end{bmatrix}^{-1} \begin{bmatrix} F_1[X^{(k-1)}] \\ \vdots \\ F_n[X^{(k-1)}] \end{bmatrix} \quad \text{--- ②}$$

Ex: solve the non-linear sys. using Newton's method

$$\left. \begin{aligned} f_1(x_1, x_2, x_3) &= 3x_1 - \cos(x_2 x_3) - 1/2 = 0 \\ f_2(x_1, x_2, x_3) &= x_1^2 - 81(x_2 + 0.1)^2 + \sin x_3 + 1.06 = 0 \\ f_3(x_1, x_2, x_3) &= e^{-x_1 x_2} + 20x_3 + \frac{10\pi - 3}{3} = 0 \end{aligned} \right\} \text{--- ③}$$

$$X^{(0)} = \begin{matrix} 0.1 & , & 0.1 & , & -0.1 \\ X_1^{(0)} & & X_2^{(0)} & & X_3^{(0)} \end{matrix}$$

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$$J = \begin{bmatrix} 3 & X_3^{(k-1)} \sin X_2^{(k-1)} X_3^{(k-1)} & X_2^{(k-1)} \sin X_2^{(k-1)} X_3^{(k-1)} \\ 2X_1^{(k-1)} & -162 [X_2^{(k-1)} + 0.1] \cos X_3^{(k-1)} & \\ -X_2^{(k-1)} e^{-X_1^{(k-1)} X_2^{(k-1)}} & -X_1^{(k-1)} e^{-X_1^{(k-1)} X_2^{(k-1)}} & 20 \end{bmatrix} \quad (4)$$

عندما $k=1$ نعوض I.C. في المعادلة (4) ونأخذ لها inverse فينتج

$$J^{-1} = \begin{bmatrix} 0.333 & 1.03 \times 10^{-5} & -1.7 \times 10^{-5} \\ 2.1 \times 10^{-3} & -0.03 & 1.5 \times 10^{-3} \\ 1.6 \times 10^{-3} & -1.5 \times 10^{-4} & 0.05 \end{bmatrix} \quad (5)$$

عندما $k=1$ نعوض I.C. في المعادلة (3) نحصل 2-

$$\left. \begin{aligned} f_1 [X^{(0)}] &= -1.19995 \\ f_2 [X^{(0)}] &= -2.26983 \\ f_3 [X^{(0)}] &= 8.46202 \end{aligned} \right\} \quad (6)$$

نعوض (5) و (6) ب (2) 2-

$$\begin{bmatrix} X_1^{(1)} \\ X_2^{(1)} \\ X_3^{(1)} \end{bmatrix} = \begin{bmatrix} 0.1 \\ 0.1 \\ -0.1 \end{bmatrix} - [J^{-1}] \begin{bmatrix} -1.19995 \\ -2.26983 \\ 8.46202 \end{bmatrix}$$

$$= \begin{bmatrix} 0.5 \\ 0.019466 \\ -0.52152 \end{bmatrix}$$

وهذه تعتبر ك I.C. عندما تصبح $k=2$ ويبدأ الحل من بدايته

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k	$X_1^{(k)}$	$X_2^{(k)}$	$X_3^{(k)}$
0	0.1	0.1	-0.1
1	0.5	0.019466	-0.52152
2	0.50004	-0.001588	-0.523557
3	0.5	-0.00001	-0.523598
4	0.5	0	=

$$X \cong \begin{matrix} 0.5 & , & 0 & , & -0.523598 \\ X_1 & & X_2 & & X_3 \end{matrix}$$

للتأكد نعرض بمعادلات السؤال

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