

**Department of Communications
Engineering**

Communication Systems

Third Year Class

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Lecture 5

Angle Modulation, PM, and FM

Angle Modulation

$$x(t) = A_c \cos(2\pi f_c t + \theta_0) \quad \text{--- (1)}$$

$$\text{or } x(t) = A_c \cos(\omega_c t + \theta_0) \quad \text{--- (1)}$$

$$\text{Let } \phi = \omega_c t + \theta_0 \quad \text{--- (2)}$$

$$\frac{d\phi}{dt} = \frac{d\omega_c t}{dt} + \frac{d\theta_0}{dt}$$

$$\boxed{\omega_c = \frac{d\phi}{dt}}$$

lets say $\omega_c =$ instantaneous angular frequency

$$\omega_c = \omega_i$$

$$\phi = \int \omega_i dt \quad \text{--- (3)}$$

now ϕ is time-dependent, thus if ϕ varies with the message, the carrier signal is then angle modulated

$$x(t) = A_c \cos(\phi) \quad \text{--- (4)}$$

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Angle Modulation

Frequency Modulation (FM)
 - frequency of the carrier is varied ~~with~~ according to the message signal

Phase Modulation (PM)
 - Phase angle of the carrier is varied according to the message signal

* FM & PM are better than amplitude modulation such as noise reduction, and efficient use of power.

* Disadvantages of FM & PM are increased bandwidth and use of complex circuits.

Applications

- ① Radio broadcasting,
- ② Two way mobile radio,
- ③ Microwave communication,
- ④ TV sound transmission,
- ⑤ Cellular radio, and
- ⑥ Satellite Communication.

Phase Modulation

We know $x(t) = A_c \cos(\omega_c t + \theta_0)$

or $x(t) = A_c \cos \phi$

where $\phi = \omega_c t + \theta_0$

* neglecting θ_0 , we get total phase angle of unmodulated carrier is

$$\phi = \omega_c t$$

* In PM, ϕ changed linearly with the message.

→ Denoting ϕ_i as the instantaneous phase angle,

$$\phi_i = \omega_c t + K_p m(t) \quad (10)$$

K_p is the constant of phase sensitivity.

$x(t) = A_c \cos[\omega_c t + K_p m(t)]$

(12)

Frequency Modulation ∞

- * The carrier frequency will be changed according to the message signal,
- * The carrier frequency will deviate linearly according to the message signal.

→ The instantaneous frequency is

$$\omega_i = \omega_c + k_f m(t) \quad (13)$$

k_f is constant of the frequency sensitivity.

Hence,
$$\phi_i = \int [\omega_c + k_f m(t)] dt$$
$$= \omega_c t + k_f \int m(t) dt$$

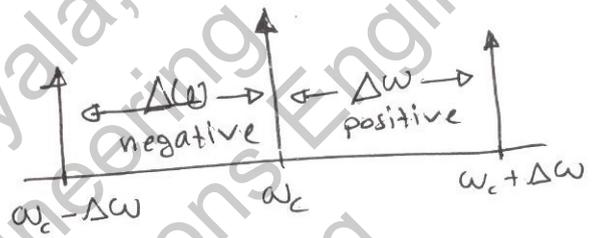
Thus:

$$x_{FM}(t) = A_c \cos \left[\omega_c t + k_f \int_0^t m(t) dt \right] \quad (14)$$

* The maximum change in ω_i (instantaneous angular freq.) from the carrier frequency ω_c is called the **frequency deviation ($\Delta\omega$)**

* The deviation is due to the message, thus, the deviation maybe +ve or -ve.

$\Delta\omega = |k_f m(t)|_{\max}$



Relationship between FM & PM

- Angle modulation is $s(t) = A_c \cos \phi_i$

- For PM $s_{PM}(t) = A_c \cos[\omega_c t + k_p x(t)]$

- For FM $s_{FM}(t) = A_c \cos[\omega_c t + k_f \int_0^t m(t) dt]$

related to each other, because in both cases there is a variation in total phase angle.

Hence, FM can be obtained using PM or PM can be obtained using FM.